Sensitivity of a Micro-scale Pump Flow Rate to Actuation Frequency Change

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Abstract

A three-dimensional computational fluid dynamics simulation for a micro-scale pump has been performed to investigate the sensitivity of the flow rate to frequency change during pump and supply phases. Applying dynamic mesh under different diaphragm actuation frequencies (8, 50, 100, 200, and 500 Hz) and sinusoidal oscillation amplitude of 6.0 µm the results showed that at frequency \( f \geq 100 \) Hz the flow separation has been formed in the diffuser direction for both supply and pump phases. At low frequency \( f \leq 50 \) Hz there is no flow separation in the diffuser or the nozzle direction. The large recirculation zone is created at the diffuser bottom wall side. The flow separation was found to be frequency and direction dependent for the micro-diffuser half angle of 5°. The net flow rate increased linearly with the frequency while the net flow per cycle was less sensitive to the change of the frequency.

Keywords

Micro-scale pump, Microelectronic cooling, CFD simulation, Frequency sensitivity

1. Introduction

A micro-scale pump is a pump system in micro-scale dimensions which is used in many applications such as biochemistry (Andersson et al., 2001), medicine (Cui et al., 2008 & Dereshgi, 2018 & Armita et al., 2022), biomedical (Gharib et al., 2023), flow separation control (Lim et al., 2005), and microelectronic cooling (Ma et al., 2008 & Verma et al, 2009). To improve the cooling process in microelectronic equipment the coolant must be forced through the micro heat exchanger or microchannels by integrating a tiny, low cost and reliable pump (Singhal et al., 2005). According to micro-scale pump classification (Laser et al., 2004) the valve-less micro-scale pump is a displacement micropump which can be actuated in several ways such as; pneumatic, thermo pneumatic, piezoelectric, electrostatic, bimetallic, and shape memory effect and electromagnetic (Yi-Fang et al., 2020). The designs of micro-scale pumps are challenging in terms of model complexity and limited knowledge of device physics on the micro-scale. Therefore, modelling strategies for micro-scale pumps have involved CFD simulation to pre-check the model design and avoid design problems (Wang et al., 2006). Some research efforts have been performed to model the valve-less micropump by different ways, for instance, lumped mass model (Olsson et al., 1999), electrical equivalent networks (Tarik et al., 1996), analytical analysis (Li et al., 2003), and numerical
or computational simulation (Hwang et al., 2008, Olsson et al., 2000, Yao et al., 2007, Zhang et al., 2005). The oscillation frequency effect on valve-less micropump flow rate has not been investigated in (Olsson et al., 2000) but the three-dimensional model was recommended to cope with the problems of low Reynolds number. However, a two-dimensional model has been employed (Zhang et al., 2005). (Yao et al., 2007) used symmetric geometry to reduce the problem size while this choice is not a good approximation for diffusers because the diffusers might have unsteady flow (Olsson et al., 2000). From the available literature, there is a lack of knowledge about flow rate sensitivity according to frequency change during a complete working cycle in a micro-scale pump. A complete working cycle of a valveless micro-scale pump consists mainly of the pump phase and supply phase. In the supply phase shown in Figure 1. (a), the diaphragm moves upward the pump chamber volume increases then the pressure decreases as a result the fluid flows into the pump chamber through the inlet and outlet diffuser/nozzle elements in such a way more flow passes through the inlet diffuser/nozzle element because it acts as a diffuser while the outlet diffuser/nozzle element acts as a nozzle. In the pump phase shown in Figure 1. (b), the diaphragm moves downward and the pump chamber volume decreases then the pressure increases so the fluid flows out from the pump chamber through the inlet and outlet diffuser/nozzle elements. In this case, the inlet diffuser/nozzle element acts as a nozzle while the outlet diffuser/nozzle element acts as a diffuser. Pressure recovery in the diffuser direction is higher than pressure recovery in the nozzle direction, and for a given pressure difference the element passes more fluid in the diffuser direction than in the nozzle direction (Gravesen et al., 1993). Hence, during a complete actuation cycle of the diaphragm over a time period which produces supply and pump phases net flow from the inlet to the outlet is generated resulting from the difference of flow rates through the inlet and outlet diffuser/nozzle elements. In the current work, a 3-D CFD simulation has been performed using the Fluent solver to solve the flow and calculate the flow rate generated under sinusoidal oscillation amplitude of 6.0 µm and different actuation frequencies of 8 Hz, 50 Hz, 100 Hz, 200 Hz and 500 Hz.

2. Model geometry

The model used in this study is based on the dimensions in (Yao et al., 2007) and consists mainly of the pump chamber, diffuser/nozzle valves, diaphragm, and the actuator besides the linking parts between the pump chamber and diffuser/nozzle elements. The isometric view is shown in Figure 2 and the geometric dimensions of the micropump model are illustrated in Table 1.

![Figure 1. Pump principle of piezoelectric valveless micropump](image1)

![Figure 2. Isometric view of the micropump model (Yao et al., 2007)](image2)
### Table 1 - Geometric dimensions of the micropump model

<table>
<thead>
<tr>
<th>Micropump part</th>
<th>Dimension (mm)</th>
</tr>
</thead>
<tbody>
<tr>
<td>In/out chamber length</td>
<td>3.95</td>
</tr>
<tr>
<td>In/out chamber width</td>
<td>0.5</td>
</tr>
<tr>
<td>Diffuser/nozzle length</td>
<td>1.25</td>
</tr>
<tr>
<td>Diffuser/nozzle throat width</td>
<td>0.04</td>
</tr>
<tr>
<td>Diffuser/nozzle wide port width</td>
<td>0.3</td>
</tr>
<tr>
<td>Diffuser/nozzle half angle</td>
<td>5°</td>
</tr>
<tr>
<td>Pump chamber diameter</td>
<td>6</td>
</tr>
<tr>
<td>Base groove diameter</td>
<td>5</td>
</tr>
<tr>
<td>Base groove height</td>
<td>0.1</td>
</tr>
<tr>
<td>PZT layer diameter</td>
<td>5</td>
</tr>
<tr>
<td>Total Micropump length</td>
<td>18</td>
</tr>
<tr>
<td>Total Micropump height</td>
<td>0.55</td>
</tr>
<tr>
<td>Total Micropump width</td>
<td>6</td>
</tr>
</tbody>
</table>

3. Theoretical analysis

3.1. Total pressure loss coefficient

The total pressure loss coefficient $\xi$ for flow through a gradually expanding diffuser, gradually contracting nozzle, or a sudden expansion or contraction in an internal flow system is defined as the ratio of pressure drop $\Delta P$ across the device to the velocity head upstream of the device (Singhal et al., 2004, Stemme & Stemme, 1993, Wu, 2003). The pressure drop in the direction of the flow is the decrease in pressure from one point to another through the internal flow system.

$$\xi = \Delta P / 0.5 \rho v^2$$

(1)

Where $\Delta P$ is the pressure drop (N/m²), $\rho$ is the fluid density (kg/m³), and $v$ is the fluid velocity (m/s).

3.2. Diffuser efficiency

The diffuser efficiency $\eta$ of a diffuser/nozzle element is defined as the ratio of the total pressure loss coefficient for flow in the nozzle direction $\xi_n$ to that for the flow in the diffuser direction $\xi_d$

$$\eta = \xi_n / \xi_d$$

(2)

From Equation (2) the flow direction will depend on the diffuser efficiency so, if $\eta > 1$ the flow will be in the diffuser direction, while $\eta < 1$ will lead to pump of the fluid in the nozzle direction.

If $\eta = 1$ this means equal pressure drop in both the nozzle and diffuser directions, leading to no flow rectification.

3.3. Flow rectification efficiency

The flow rectification efficiency of a valveless micropump $\chi$ is the ability of the valveless micropump to direct the flow in one specific direction. It can be expressed as:

$$x = (Q_+ - Q_-)/(Q_+ + Q_-)$$

(3)

Where $Q_+$ is the flow rate in the forward and $Q_-$ is the flow rate in the backward directions. The higher $\chi$ corresponds to better flow rectification.

3.4. Flow governing equations

Equations of motion for 3-D, incompressible, viscous, unsteady state flow in Cartesian (x-y-z) co-ordinates have been used as explained in (Versteeg & Malalasekera, 1995) to simulate the laminar flow inside the valveless micropump.

- Continuity
  $$\frac{\partial \rho}{\partial t} + \nabla \cdot (\rho \mathbf{U}) = 0$$
  (4)

- Navier-Stokes equations in laminar form
  In x-direction:
  $$\frac{\partial (\rho \mathbf{u})}{\partial t} + \nabla \cdot (\rho \mathbf{u} \mathbf{U}) = - \nabla \cdot \mathbf{P} + \nabla \cdot (\mu \nabla \mathbf{u})$$
  (5.a)

  In y-direction:
  $$\frac{\partial (\rho \mathbf{v})}{\partial t} + \nabla \cdot (\rho \mathbf{v} \mathbf{U}) = - \nabla \cdot \mathbf{P} + \nabla \cdot (\mu \nabla \mathbf{v})$$
  (5.b)

  In z-direction:
  $$\frac{\partial (\rho \mathbf{w})}{\partial t} + \nabla \cdot (\rho \mathbf{w} \mathbf{U}) = - \nabla \cdot \mathbf{P} + \nabla \cdot (\mu \nabla \mathbf{w})$$
  (5.c)

Where $P$, $\rho$, $\mu$, $\mathbf{U}$, $u$, $v$, $w$ and $\mathbf{U}$ are pressure, fluid density, dynamic viscosity, standard spatial grad operator, velocity component in x-direction, velocity component in y-direction, velocity component in z-direction and velocity vector ($u_i + v_j + w_k$), respectively.

4. CFD Simulation

4.1. Diaphragm deflection

The source of actuation of the fluid inside the pump chamber is the piezoelectric actuator which consists of
the piezoelectric disc attached to the elastic membrane. When sinusoidal alternate voltage \( V = V_o \sin(2ft) \) is applied to the piezoelectric layer the membrane will expand or contract, and then the pump chamber volume and pressure are changed over an interval of time as a result fluid flow will be generated through the whole micropump by the function of diffuser/nozzle elements. A user-defined function (UDF) has been used to control the deflection of the oscillating membrane according to the deflection amplitude \( A \) and frequency \( f \). The deflection amplitude is the most important parameter for the simulation so the maximum center deflection of the diaphragm according to the voltage applied has been taken from (Zhang & Wang, 2006) as shown in Figure 3. The diaphragm was assumed to move in a sinusoidal fashion and simulated by:

\[
y(r, t) = A \cos\left(\frac{\pi r}{D}\right) \sin(2\pi ft)
\]

(6)

Where \( y \) is the maximum diaphragm deflection, \( r \) is the radial distance, \( t \) is the flow time and \( D \) is the actuator diameter.

4.2. Geometry and grid generation

GAMBIT as an operator interface has been used to create the 3-D geometry and then generate the mesh for the model that is used to solve the flow. The geometry has been created by using the “bottom-up” approach. The unstructured mesh has been generated by using the tetrahedral/hybrid elements and TGrid type scheme. The mesh for the typical model consists of (76019) total number of grid nodes and (351442) total number of elements or cells.

4.3. Boundary conditions

The inlet and the outlet boundary condition have been set to be inlet-vent and outlet-vent, respectively because both of the inlet and outlet ports in the micropump work as inlet during the supply phase and outlet during the pump phase according to the diaphragm oscillation. The flow is assumed to be unsteady, viscous, and laminar with no-slip conditions near the wall. All the walls of the micropump are assumed to be fixed except for the diaphragm, which is an oscillating diaphragm and the oscillation of this diaphragm is governed by a compiled user defined-function to simulate the diaphragm oscillation using dynamic mesh.

4.4. Time step settings

Time step size \( \Delta t \) is the key for the solution accuracy in unsteady flow problems. Hence, the value of time step size \( \Delta t \) is changed according to the change in frequency and number of time steps \( N \) by applying the relation (Yao et al., 2007):

\[
\Delta t = \frac{1}{f \times N}
\]

(7)

According to Equation (7) the value of the proper time step size at a certain frequency value was calculated at constant \( N = 400 \) and different frequency values \( f \).

4.5. Mesh sensitivity

Grid independence studies were performed to minimize the computational effort. Three different meshes with different numbers of elements mesh 1 of (56845 elements), mesh 2 of (351442 elements), and mesh 3 of (918439 elements) have been examined for grid independence. The flow rate is plotted as a function of time at zero back pressure. Figure 4 illustrates the outlet flow rate for the three different meshes at a frequency of 50Hz and amplitude of 70 µm. From Figure 4 it is obvi-
ous that there is some difference in the flow rates resulting from the three different meshes. The coarse mesh (mesh 1) has not been used to avoid the deviation of the flow rate at a steady state from the mesh independence. Mesh 3 is very fine and needs high computational effort without any significant improvement of the net flow rate so that mesh 2 of (351442 elements) has been selected to simulate the unsteady flow in the valve-less micropump.

Figure 4. Grid independence for flow rate at outlet for 50 Hz and 70 µm

4.6. Validation

The flow visualization from the experimental work in (Chen-li & Zone, 2007) has been compared with the current CFD simulation using Fluent solver. A combined structure and unstructured mesh of 53173 elements has been used to perform the simulation. The inlet boundary condition was set to be a pressure inlet of 550 pa gauge pressure, the outlet boundary condition was set to be a pressure outlet of 0 pa gauge pressure and the Reynolds number was 20.2. The streamtraces resulted from the CFD work compared with the experimental flow visualization and showed a reasonable agreement as shown in Figure 5.

Figure 5. Diffuser flow separation comparison for validation

The rectification efficiency ($\chi$) has been taken as a performance indicator. The rectification efficiency of diffuser-nozzle micropumps reported in the literature is generally between 1% and 20% (Singhal et al., 2004) and the rectification efficiencies for these models range from 2.75% to 13.1%, which are consistent with the reported range.

5. Results and discussion

Inlet and outlet flow rates at 500 Hz frequency and 6µm amplitude are illustrated in Figure 6 the complete cycle consists of the pump phase and the supply phase so the velocity vectors and stream traces are depicted for the two phases at a frequency of 500 Hz.

5.1. Pump phase

In this phase, the maximum deflection was achieved downward and the flow was subjected to maximum pump force. The maximum velocity occurred in the outlet diffuser. The maximum velocity magnitude at the inlet diffuser throat during the pump phase was less than the velocity magnitude at the outlet diffuser throat which means more flow produced in the outlet port according to the mass conservation law. Stream traces are used to illustrate the flow separation in the valve-less micropump as an internal flow system. During the pump phase at the 500 Hz case, no recirculation zones or flow separations were formed in the inlet diffuser and the flow was attached to the side walls as shown in Figure 9. In contrast, a big recirculation zone covering about 85 percent of the length of the diffuser bottom wall occurred in the outlet diffuser. Two main recirculation regions and two secondary recirculation zones were formed in the pump chamber the first main one was located at 0.00675 m of the pump length near the inlet diffuser exit its rotation direction was clockwise opposite to the flow direction from the pump chamber to the inlet diffuser.
5.2. Supply phase

The maximum velocity magnitude achieved in the inlet diffuser throat. During the supply phase, the flow came into the pump chamber from the diffuser/nozzle elements as the pressure outside the pump chamber was higher than the pressure inside the pump chamber because the maximum deflection occurred upward and the flow was subjected to the minimum pump force. The maximum velocity magnitude at the outlet diffuser throat was less than that at the inlet diffuser throat then more flow passed from the inlet diffuser to the pump chamber. From Figure 9 during the supply phase at the 500 Hz case, the recirculation zones were created in the inlet diffuser. The big recirculation zone and flow separation generated at the diffuser bottom wall covered about 84 percent of the length of the diffuser bottom wall. The two small recirculation zones generated at the top wall covered about 42 percent of the length of the diffuser wall. In contrast, there was no recirculation zone occurred at the outlet diffuser. From Figure 8 the two main recirculation zones that were observed in the pump phase shrank due to the change of the working phase from pump to supply and another two recirculation regions were formed closer to the inlet and outlet diffusers.

For the full range of frequency from 8 Hz to 500 Hz, there were no recirculation zones or flow separation in the diffuser/nozzle elements at low frequency $f \leq 50$ Hz. The onset of the flow separation started at $f \geq 100$ Hz. While the recirculation regions for 100 Hz were observed in the outlet diffuser during the pump phase and in the inlet diffuser during the supply phase, no recirculation regions were observed in the nozzle direction (converging direction) during the pump or supply phase. Further increase in the excitation frequency leads to an increment of the recirculation zone size and secondary recirculation zone formation in the inlet diffuser during the pump phase as shown in Figure 9.
6. Conclusions

A 3-D CFD flow simulation has been performed to investigate the sensitivity of the flow rate to frequency change during pump and supply phases in a micro-scale pump. The net mass flow rate increased linearly with frequency and the maximum generated flow rate at a frequency of 500 Hz and amplitude of 6 µm was 1.96 µL/min. The net mass flow rate per cycle was less sensitive to the frequency change. No flow separation occurred in the nozzle direction (converging direction) for flow under the full range of frequency 8–500 Hz. In contrast, the flow separation occurred in the diffuser directions for both pump and supply phases at $f \geq 100$ Hz.

References


